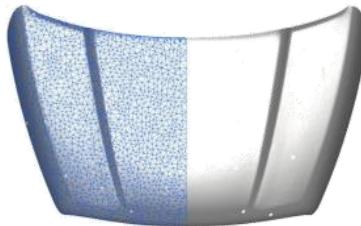


## 3D光學量測 應用於MIM製程檢測

Kevin Lin 林彥宇







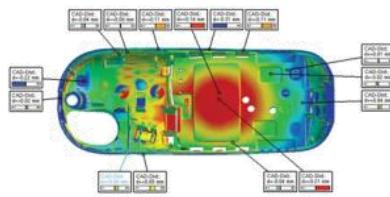
## 逆向工程 (RE)

- ATOS 光學掃描
- TRITOP 光學式三次元
- Imageware 逆向建面



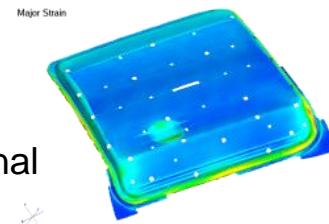
## 自由造型設計 (ID)

- FreeForm 觸覺式設計



## 電腦輔助檢測 (CAV)

- ATOS 照相式掃描
- TRITOP 光學式三次元
- GOM Inspect Professional 參數式檢測軟體



## 變形檢測 (Deformation)

- ARAMIS 應變分析
- ARGUS 銻金成型性分析
- PONTOS 動態點座標量測



## 快速成型設備 (RP)

- SLA 樹脂雷射硬化成型
- SLS 粉末雷射燒結成型
- Projet 樹脂列印成型
- Zprinter 粉末列印成型

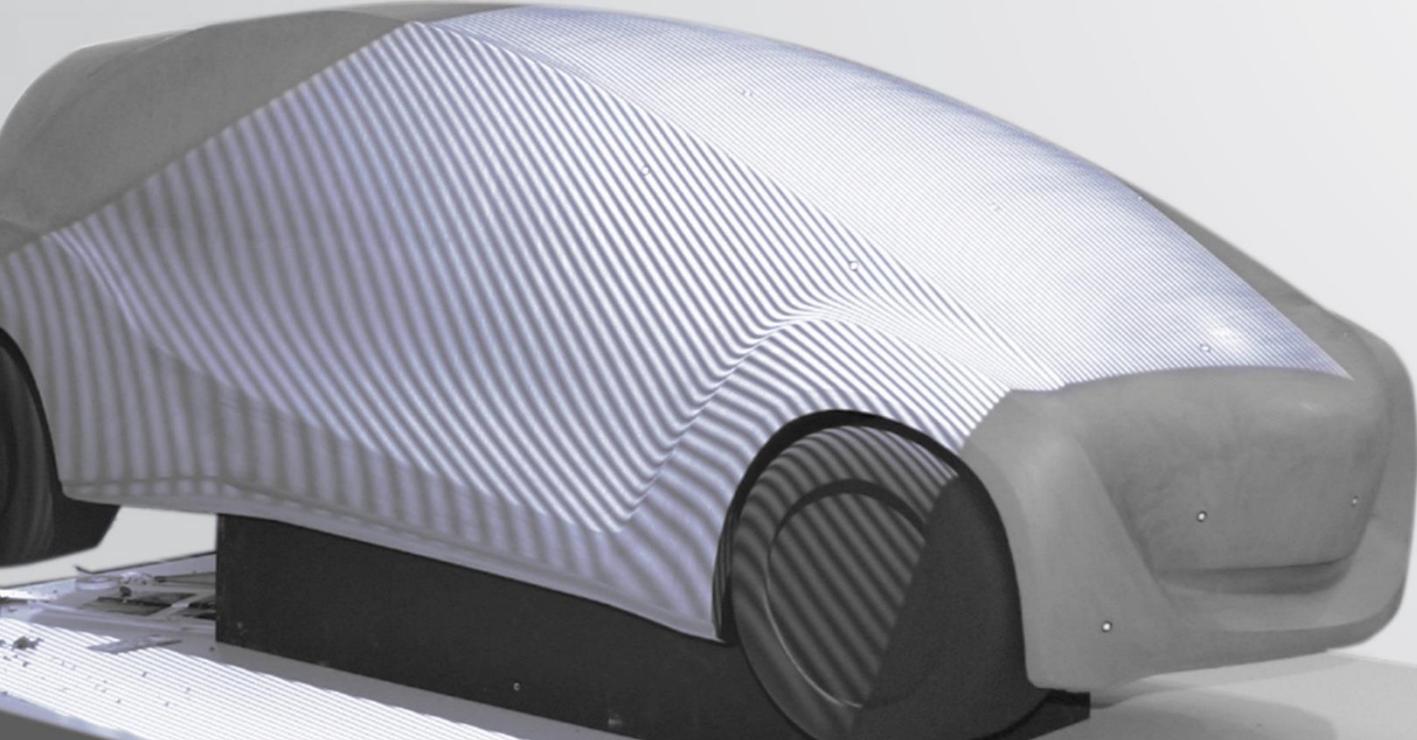


## 移動式三次元 (PCMM)

- FARO GAGE
- FARO ARM
- FARO Laser Tracker

## 3D測量系統

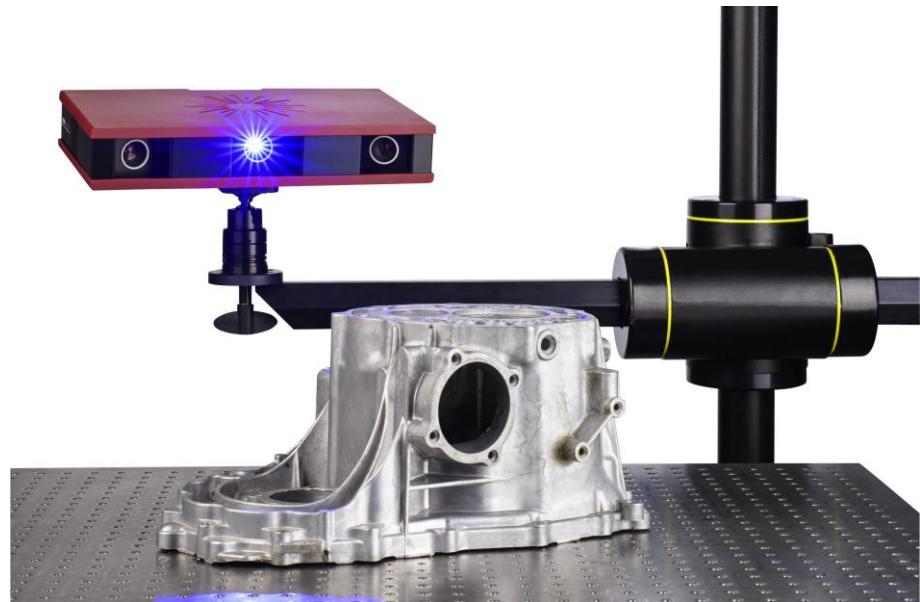
ATOS Core



# ATOS Core 高精度3D量測系統



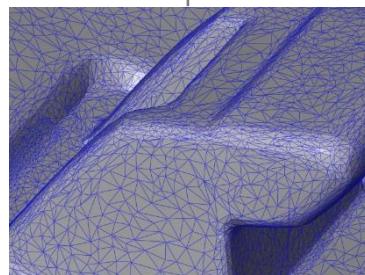
- Optical 3D scanner for three-dimensional component measurement and inspection
- Any object size, surface characteristics and component complexity
- Full-field, precise 3D coordinates
- Non-contact



# ATOS Core 高精度3D量測系統



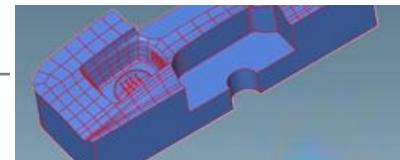
3D列印 + 3D掃描



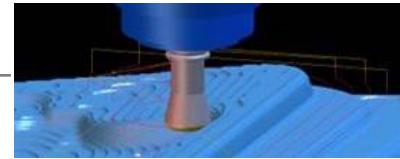
## 3D Mesh (STL)

High resolution for finest details  
Measurement of small radii

Data for follow-on processes



Additive Manufacturing

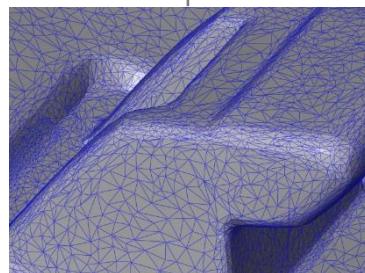


CNC Machining



Quality Control

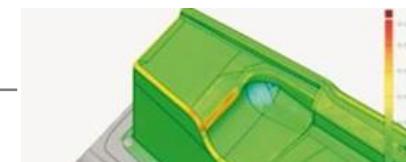
# ATOS Core 高精度3D量測系統



## 3D Mesh (STL)

High resolution for finest details  
Measurement of small radii

**Data for follow-on processes**

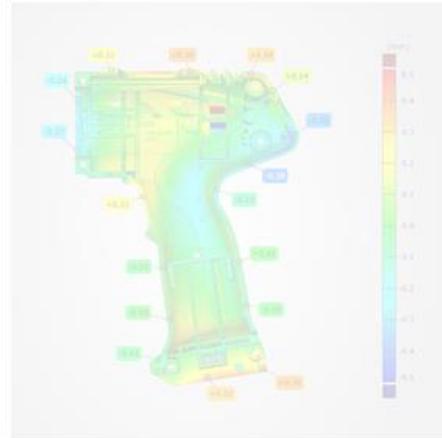


## Quality Control

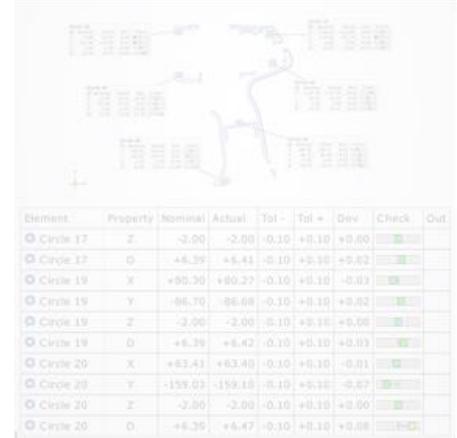
# ATOS Core 高精度3D量測系統



**Step 1  
Measurement**



**Step 2  
Evaluation**



**Step 3  
Inspection  
Report/Table**

# ATOS Core 高精度3D量測系統

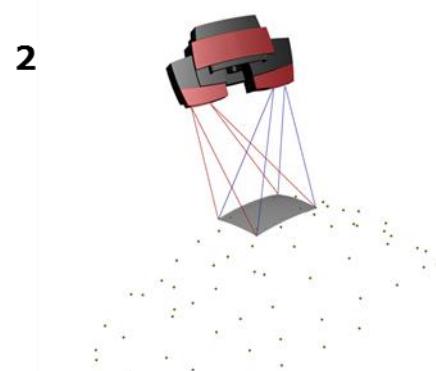


1  
Fringe projection supplies precise  
3D coordinates for each pixel

# ATOS Core 高精度3D量測系統



Fringe projection supplies  
precise  
3D coordinates for each pixel



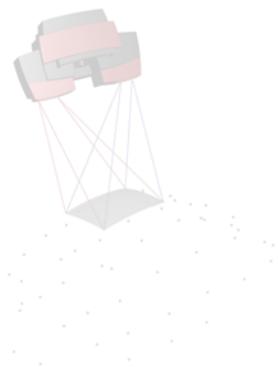
Approx. 2 seconds for each  
individual measurement of  
12 million points

# ATOS Core 高精度3D量測系統



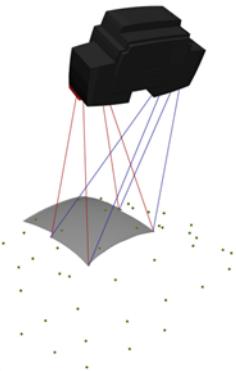
Fringe projection supplies  
precise  
3D coordinates for each pixel

2



Approx. 2 seconds for each  
individual measurement of 12  
million points

3

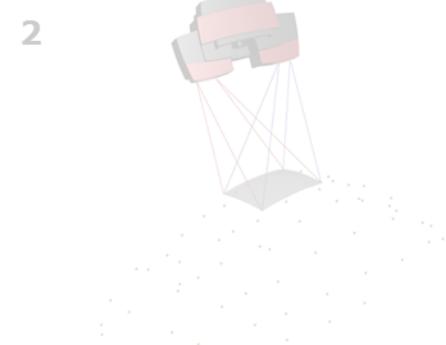


Measurement from different  
directions

# ATOS Core 高精度3D量測系統



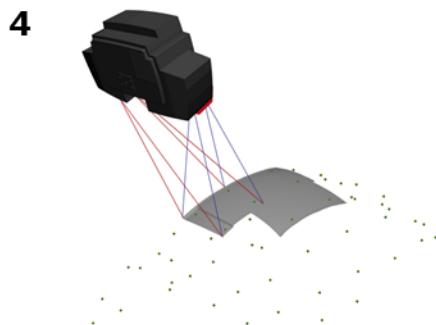
1  
Fringe projection supplies precise 3D coordinates for each pixel



2  
Approx. 2 seconds for each individual measurement of 12 million points



3  
Measurement from different directions

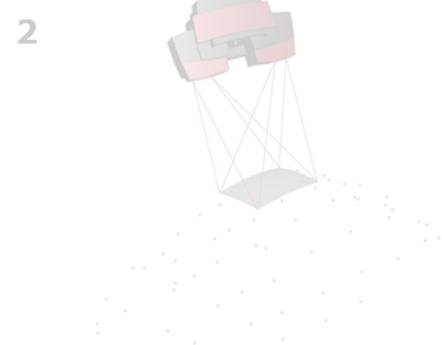


4  
Automatic transformation of single measurements

# ATOS Core 高精度3D量測系統



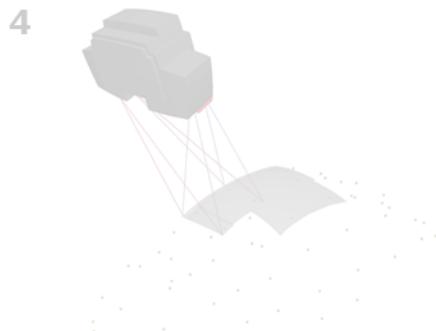
Fringe projection supplies precise 3D coordinates for each pixel



Approx. 2 seconds for each individual measurement of 12 million points



Measurement from different directions



Automatic transformation of single measurements

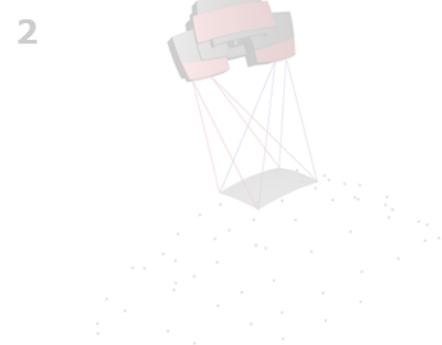


Polygonization of individual measurements to eliminate overlapping areas

# ATOS Core 高精度3D量測系統



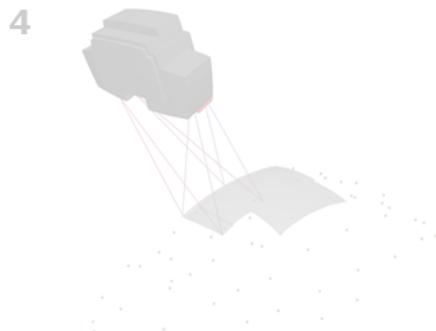
Fringe projection supplies precise 3D coordinates for each pixel



Approx. 2 seconds for each individual measurement of 12 million points



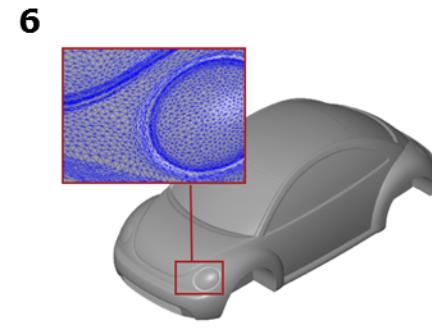
Measurement from different directions



Automatic transformation of single measurements



Polygonization of individual measurements to eliminate overlapping areas

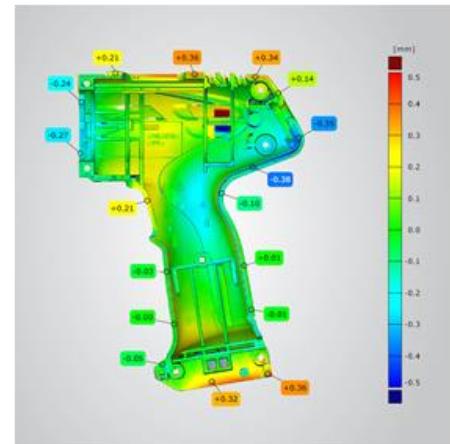


**The result:**  
A complete 3D point cloud (STL triangular mesh)

## ATOS Core 高精度3D量測系統



## Step1 **Measurement**



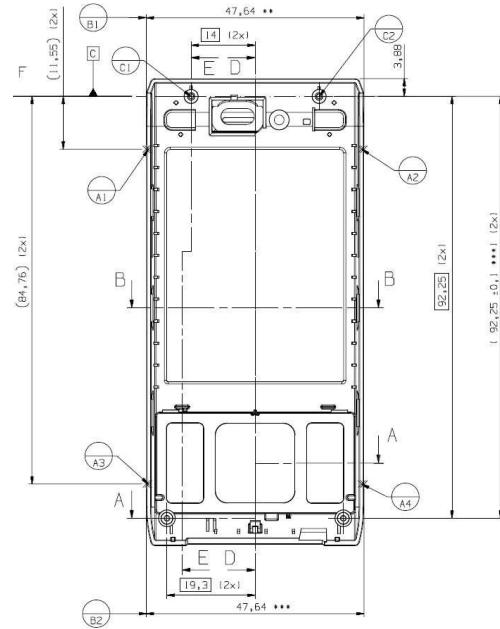
## Step 2 **Evaluation**

Element	Property	Nominal	Actual	Tol	Tol +	Tol -	Dev	Check	Out
Circle 17	Z	-2.00	-2.00	-0.10	+0.10	+0.00	+0.00	<span style="background-color: green;">■</span>	
Circle 17	D	+6.39	+6.41	-0.10	+0.10	+0.02	+0.02	<span style="background-color: green;">■</span>	
Circle 19	X	+80.39	+80.27	-0.10	+0.10	-0.03	-0.03	<span style="background-color: green;">■</span>	
Circle 19	Y	-86.70	-86.68	-0.10	+0.10	+0.02	+0.02	<span style="background-color: green;">■</span>	
Circle 19	Z	-2.00	-2.00	-0.10	+0.10	+0.00	+0.00	<span style="background-color: green;">■</span>	
Circle 19	D	+6.39	+6.42	-0.10	+0.10	+0.03	+0.03	<span style="background-color: green;">■</span>	
Circle 20	X	+63.41	+63.40	-0.10	+0.10	-0.01	-0.01	<span style="background-color: green;">■</span>	
Circle 20	Y	-159.03	-159.10	-0.10	+0.10	-0.07	-0.07	<span style="background-color: yellow;">■</span>	-1
Circle 20	Z	-2.00	-2.00	-0.10	+0.10	+0.00	+0.00	<span style="background-color: green;">■</span>	
Circle 20	D	+6.39	+6.47	-0.10	+0.10	+0.08	+0.08	<span style="background-color: yellow;">■</span>	-1

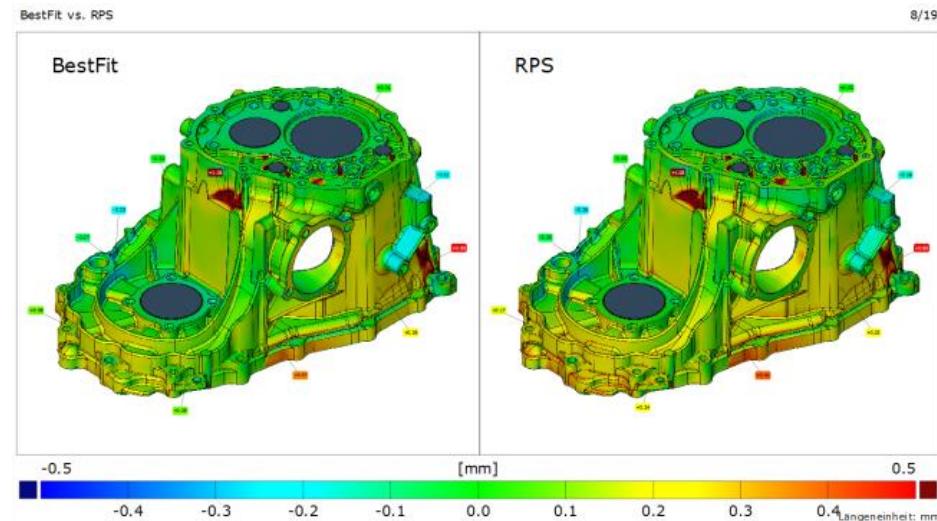
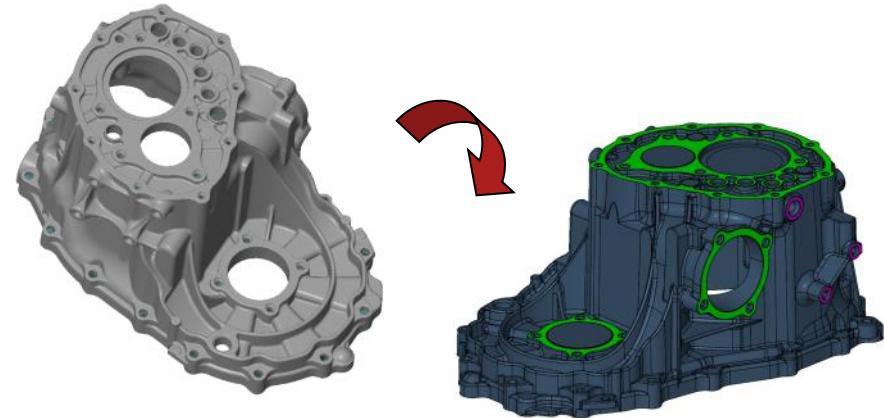
### **Step 3 Inspection Report/Table**

## 多樣的定位方式

- Flexible alignment of measurement data to CAD
- Different alignment options, RPS, 3-2-1, best fit,...

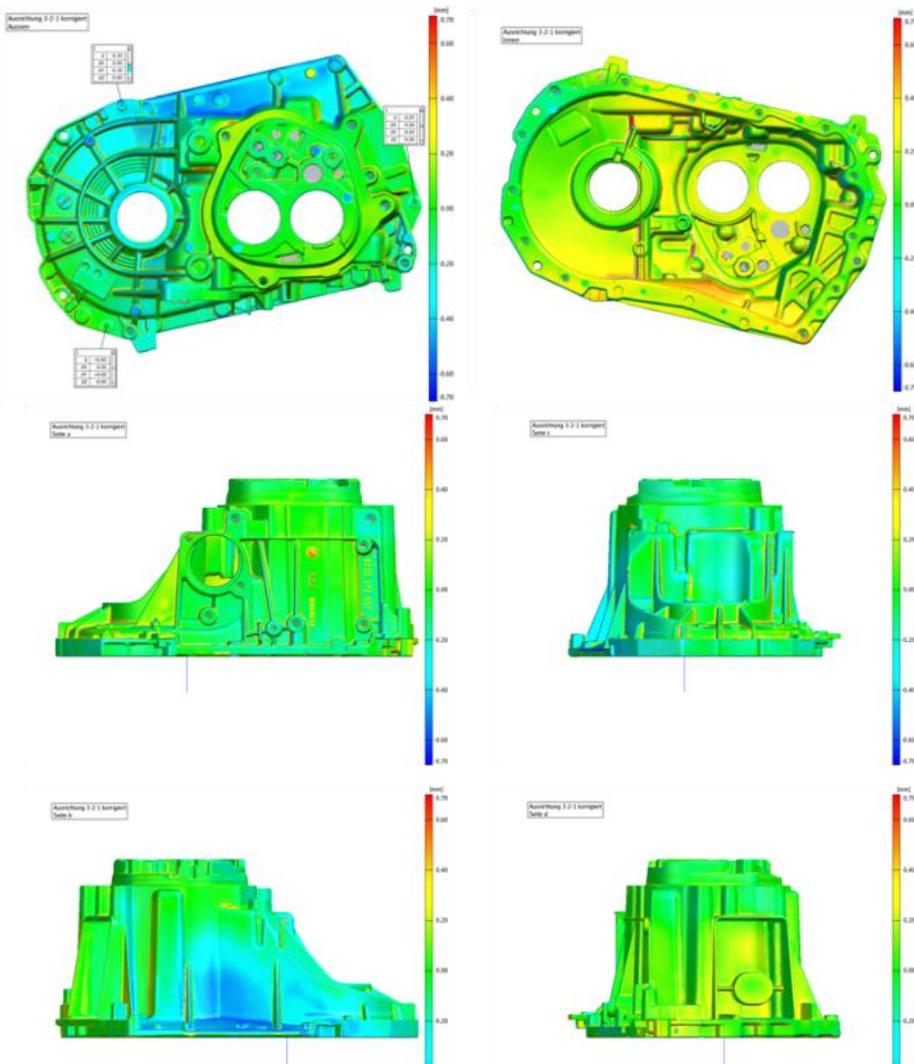


光學元件曲面與機構3D量測新技術



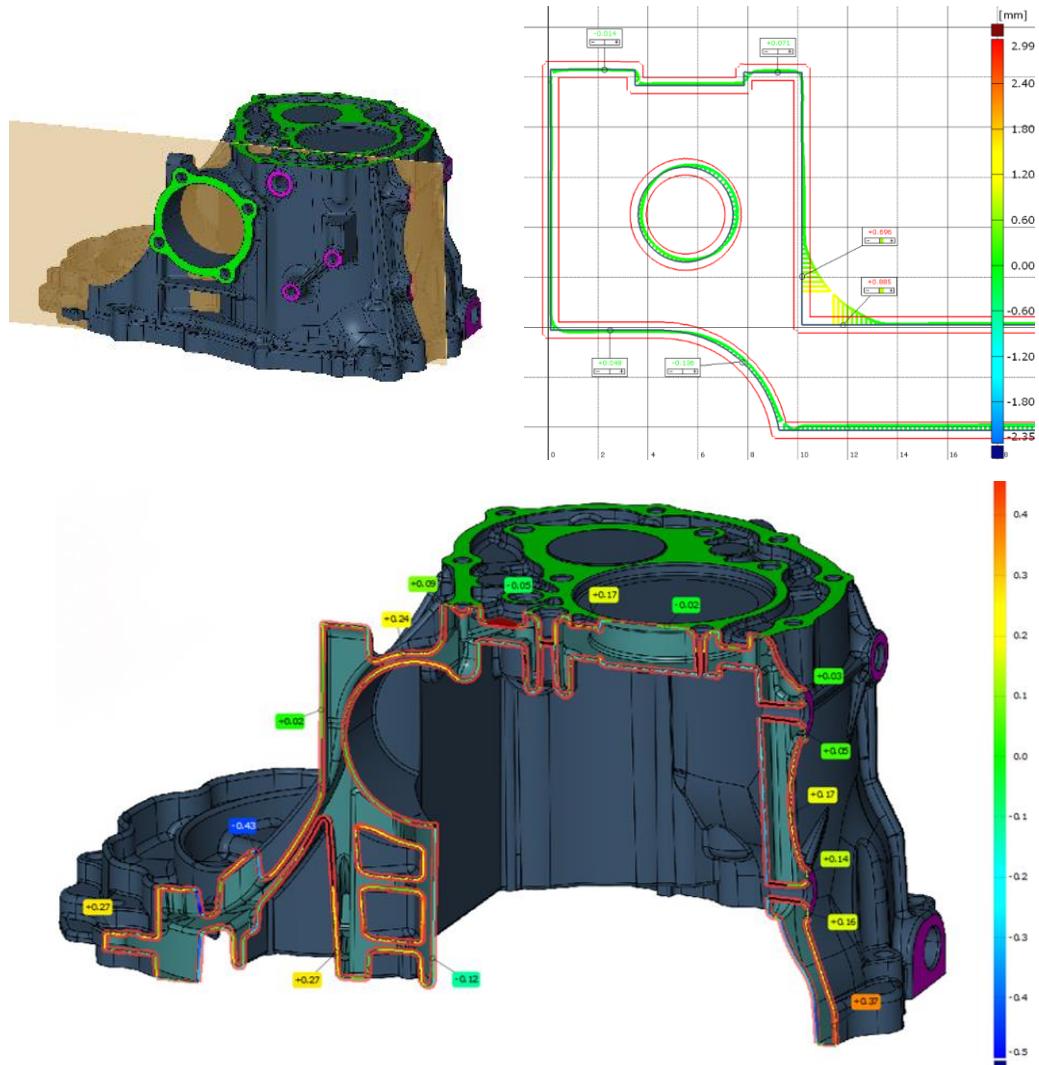
## 分析及檢測-誤差色彩圖

- 與CAD全曲面比對誤差色彩圖
- 3D曲面及尺寸管制
- 翹曲變形
- 凸陷及縮痕
- 縮水



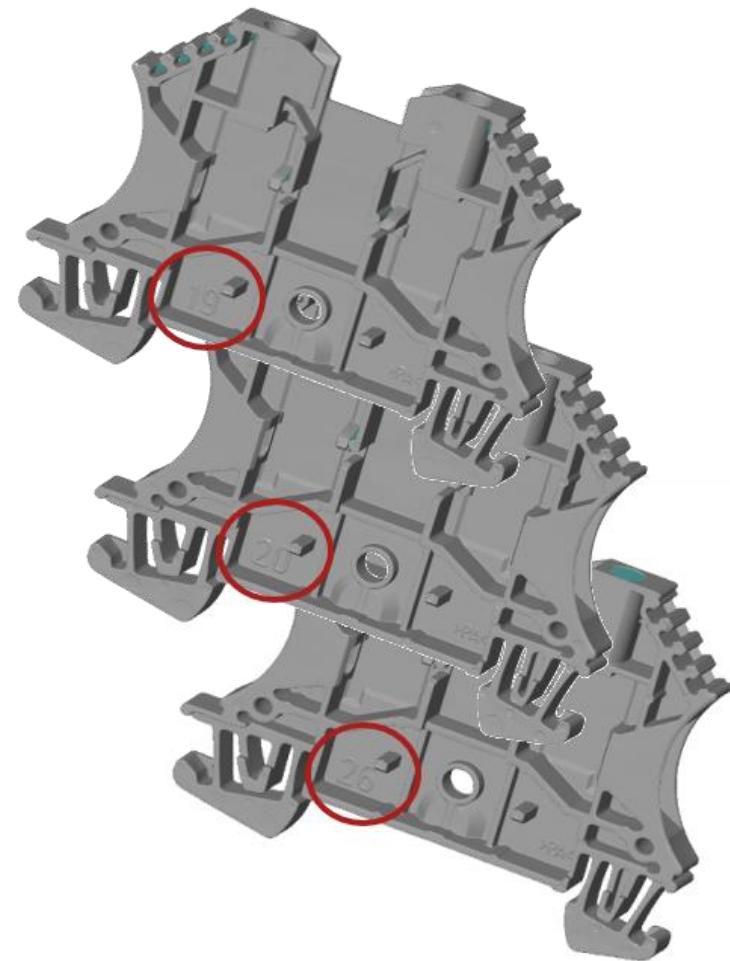
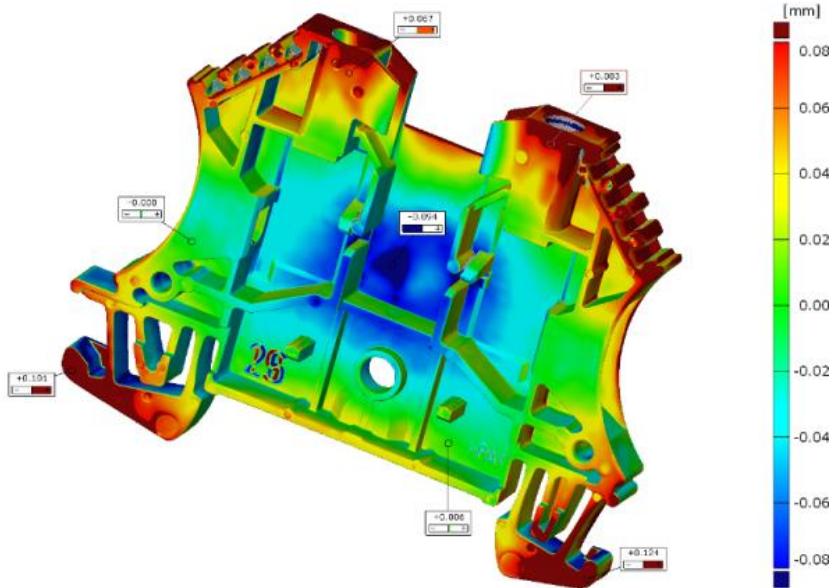
## 分析及檢測-剖面分析

- 任意位置作2D檢測剖面
- 點資料剖與CAD剖面比對
- 剖面位置在模型顯示
- 針狀圖
- 誤差標記點
- 公差帶顯示



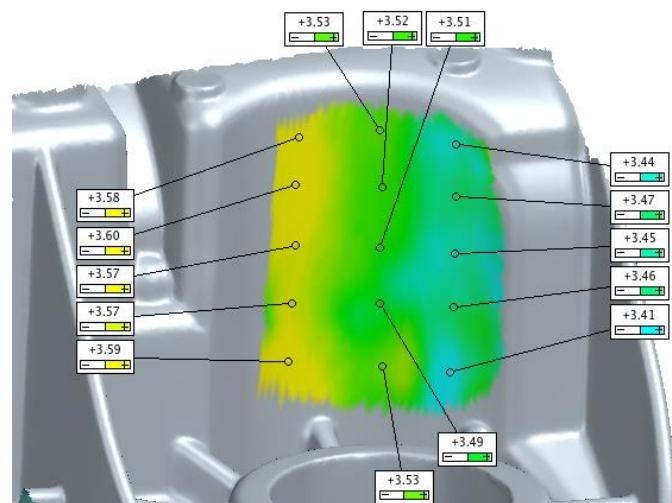
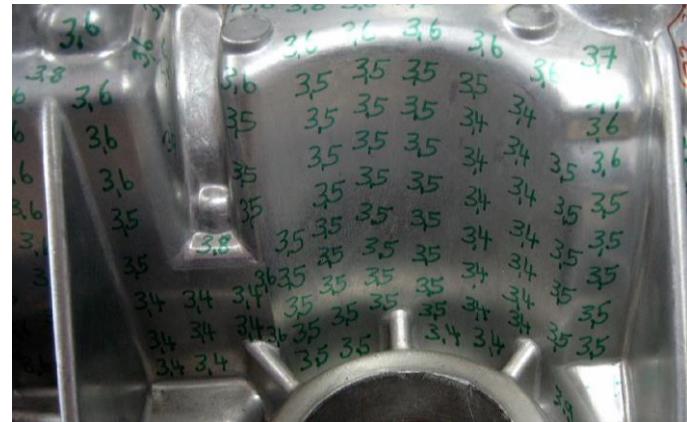
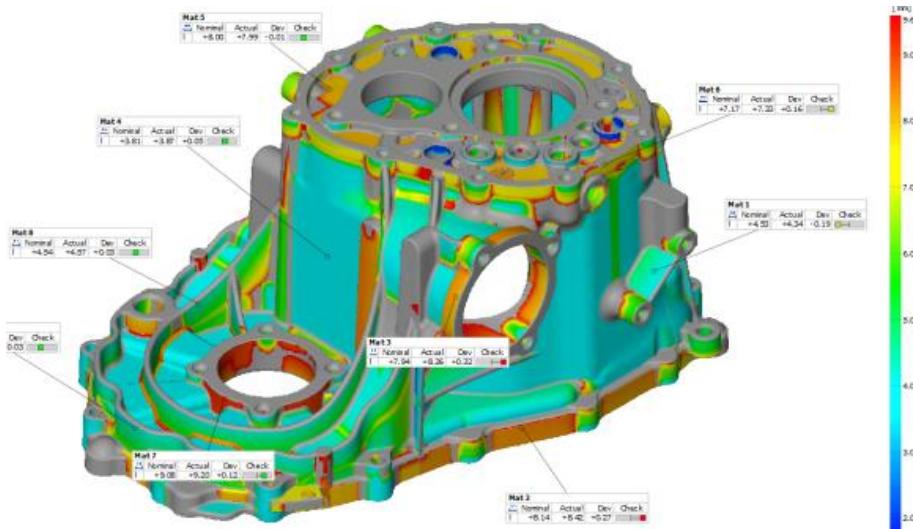
## 分析及檢測-點資料互相比對

- 比對不同模穴的射出件
- 比對不同供應商的零件
- 改變射出條件前後的工件比對



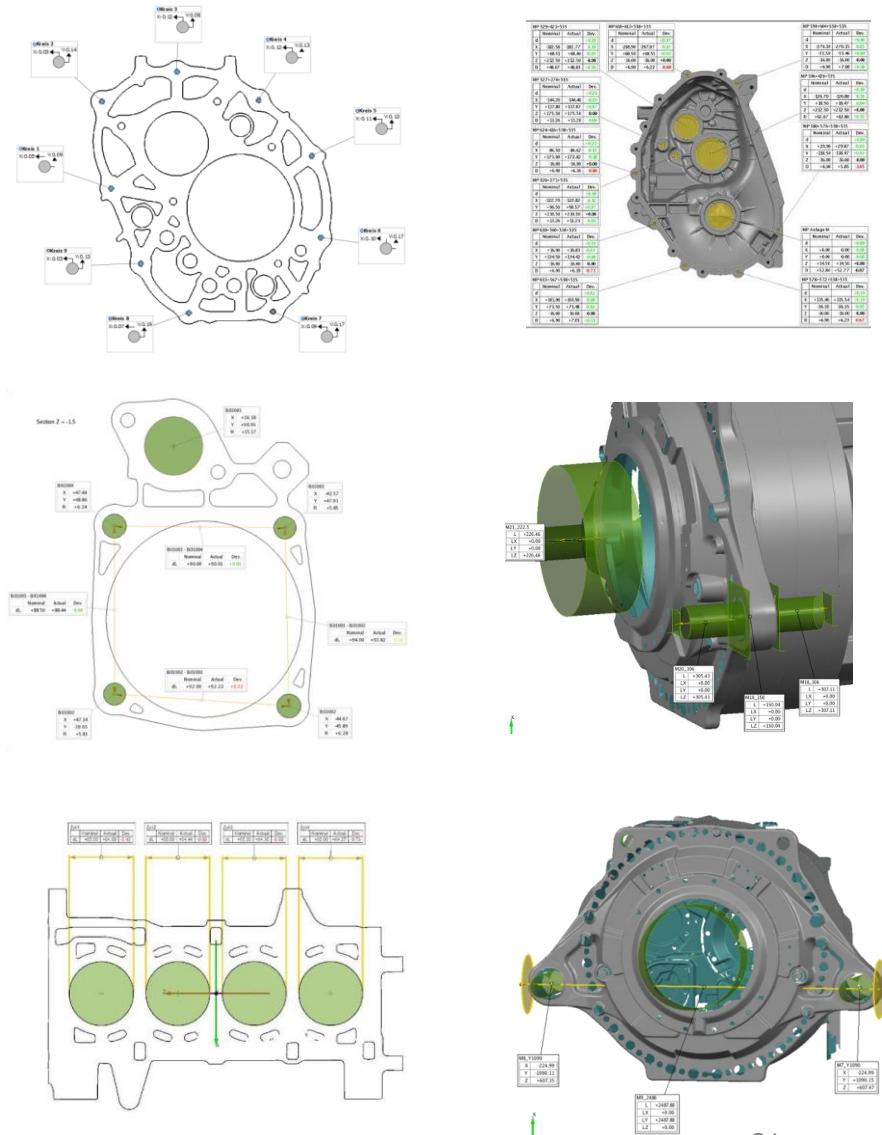
## 分析及檢測-厚度分析

- 全域的材料肉厚分析 - 識別凹陷及縮痕位置, 材料堆積區域, 縮孔發生位置



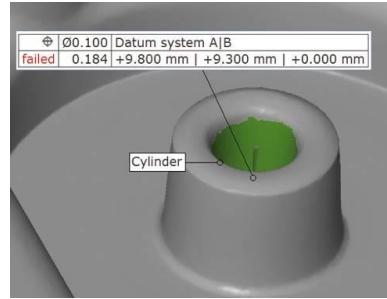
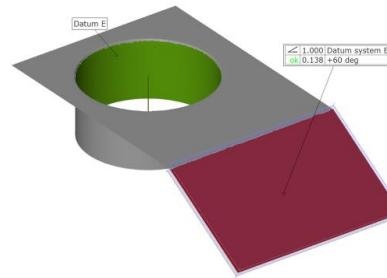
# 分析及檢測-尺寸量測

- 完整的 FAI 三次元檢測報表
  - 位置尺寸
  - 距離尺寸
  - 角度尺寸
  - 直徑尺寸
- 幾何特徵的建立
  - Best-Fit
  - Cheby-Fit
  - 手動建立
- 虛擬尺規
- 3D尺寸量測或2D剖面尺寸量測
- 自定義報表內容及格式

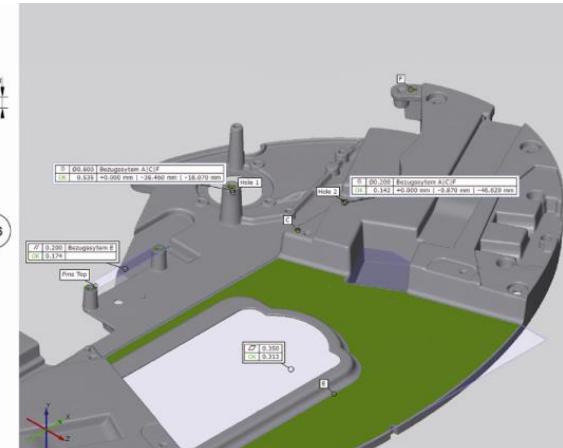
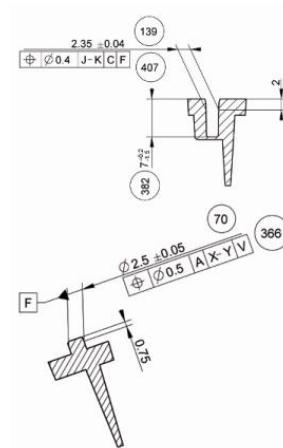


# 分析及檢測-幾何公差與尺寸(GD&T)

- 在密集網格資料上依選取範圍計算 GD&T 數值而非只是由少數點計算
- 快速及自動特徵選取及擬合
- 可建立多個參考座標系
- 直覺容易解讀的視覺化GD&T量測結果顯示
- 依循 EN ISO 1101 & ASME Y 14.5 標準

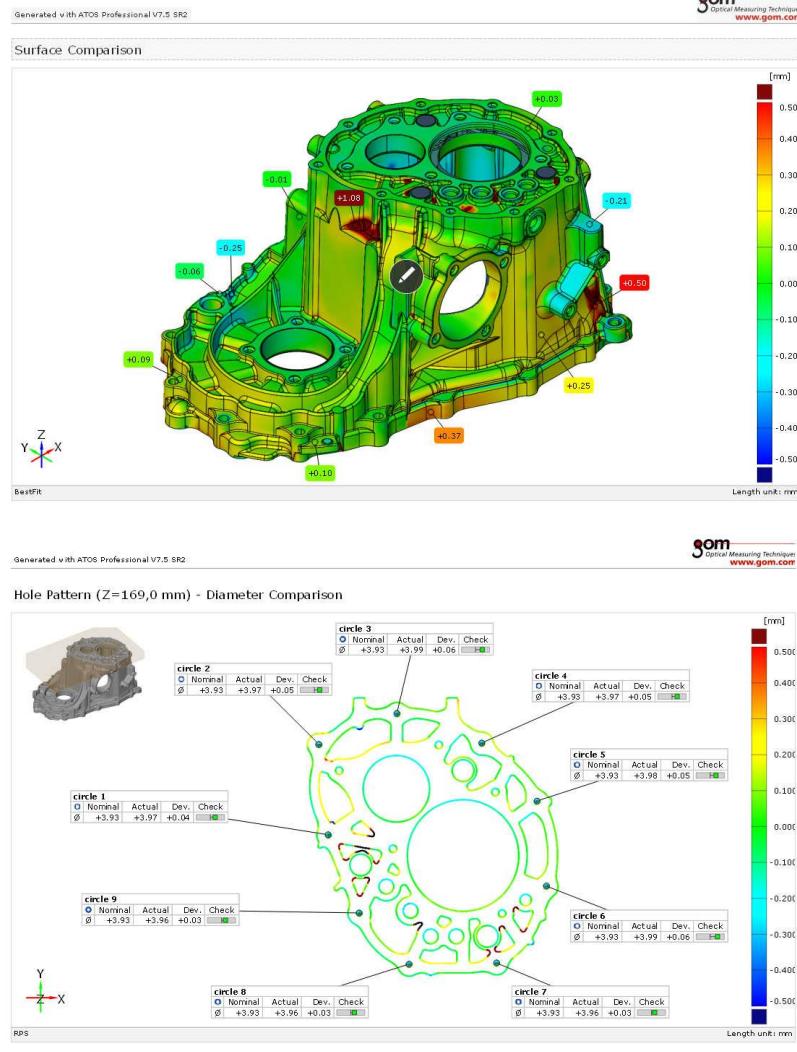


- Straightness...
- △ Flatness...
- Roundness...
- ❖ Cylindricity...
- // Parallelism...
- ⊥ Perpendicularity...
- ↙ Angularity...
- ⊕ Position...
- ◎ Concentricity...
- ≡ Symmetry...
- ⌚ Line Profile...
- ⌚ Surface Profile...
- ↗ Run-Out...
- ↖ Total Run-Out...



# 分析及檢測-檢測報表

- 建立畫面截圖或是檢測內容表單
- 容易自定義的報表內容
- 單一報表可以建立多張截圖作為比較
- 表單自動由顯示畫面或選取的物件產生
- 所有的截圖與表單與3D畫面連結並可自動更新
- 同一報表可以有多個對位方式
- 輸出 PDF 或 JPG



## 試模應用



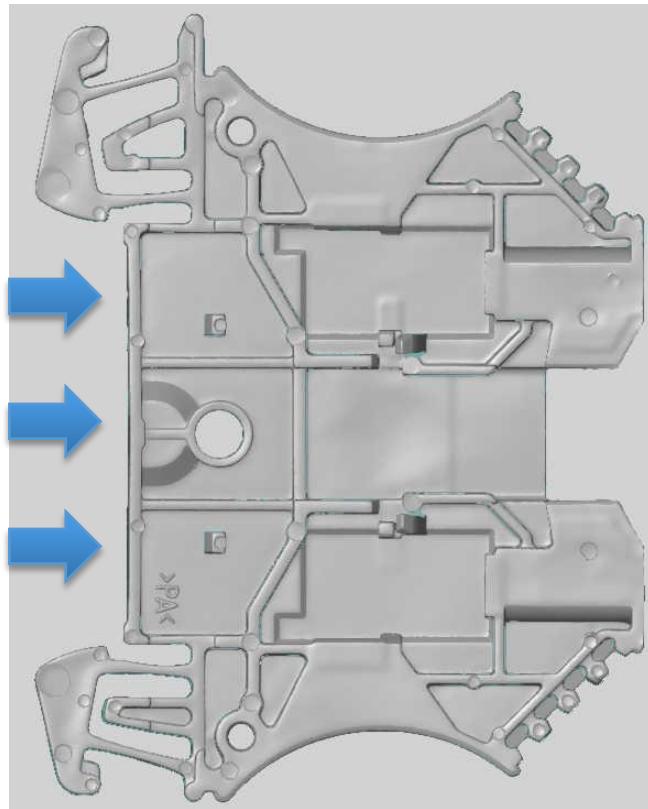
成型條件檢測用於先行決定何種條件式最佳成型條件。在階段性試模後先行檢測成品，此時不需要量測所有尺寸，只需透過色彩圖即可分析結果，節省量測尺寸時間。

### 試模條件影響

- 成型條件差異比較
- 保壓時間差異比較
- 進料點差異
- 不同模穴比較

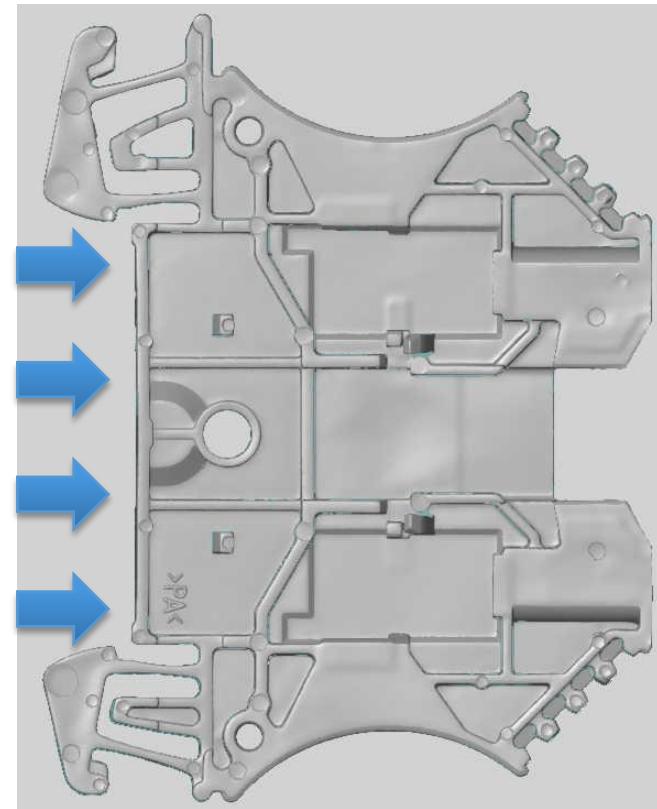
3個進料點

進  
料  
點

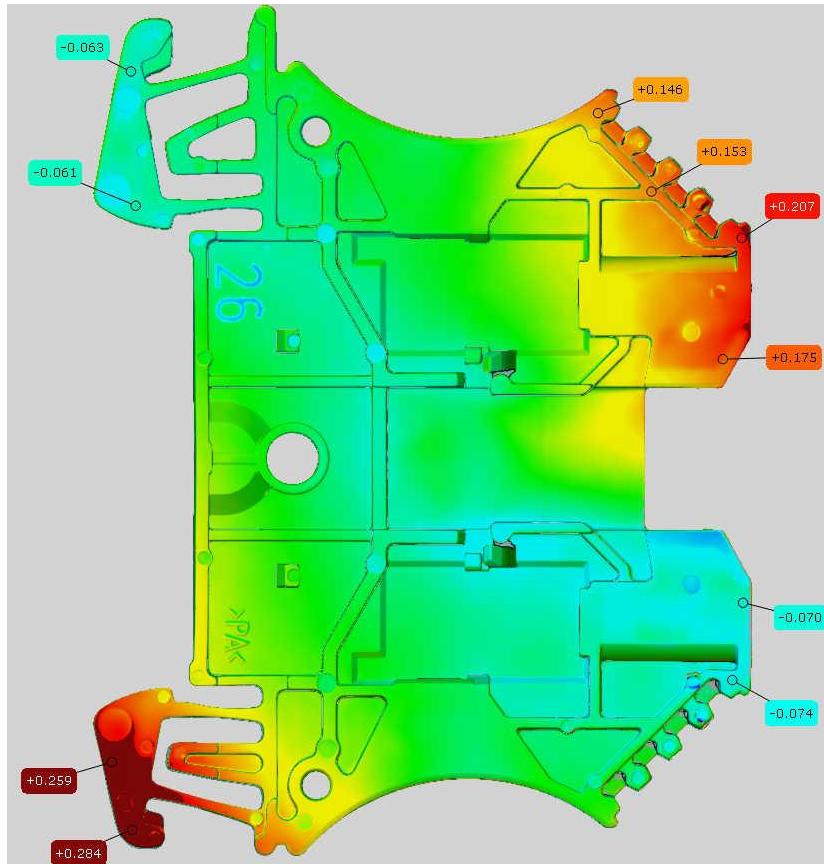


4個進料點

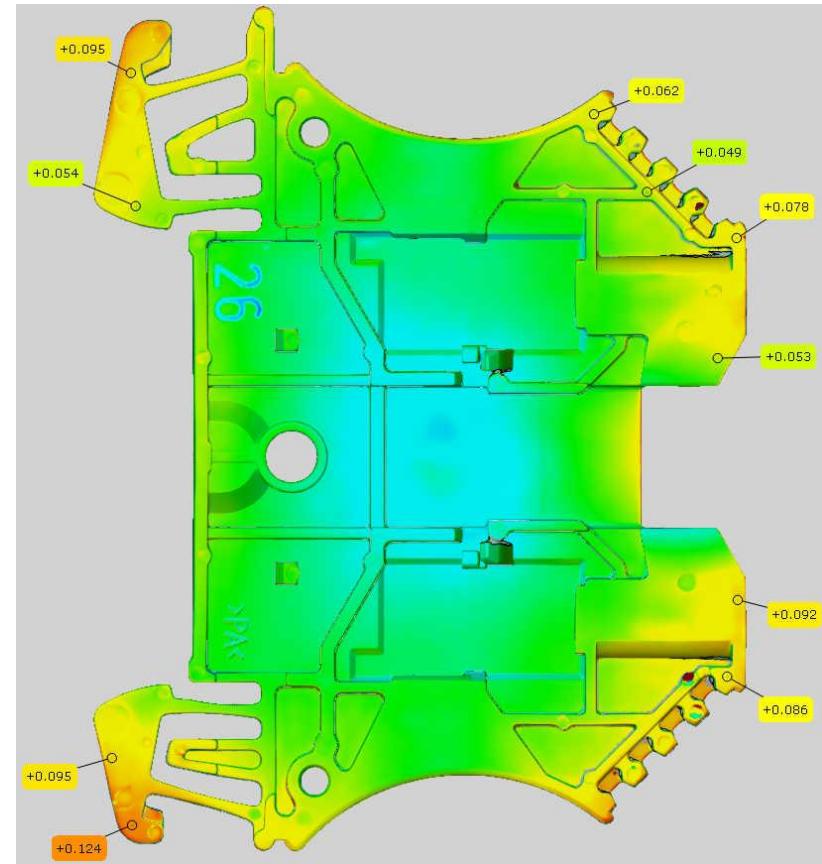
進  
料  
點



## 3個進料點



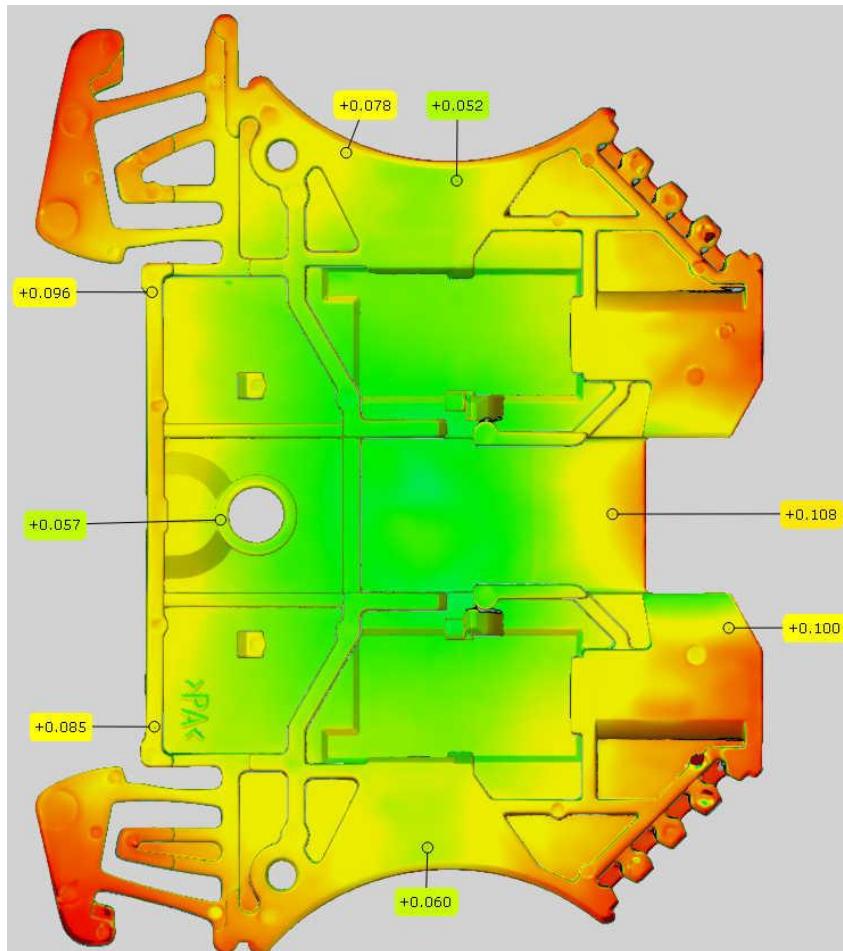
## 4個進料點



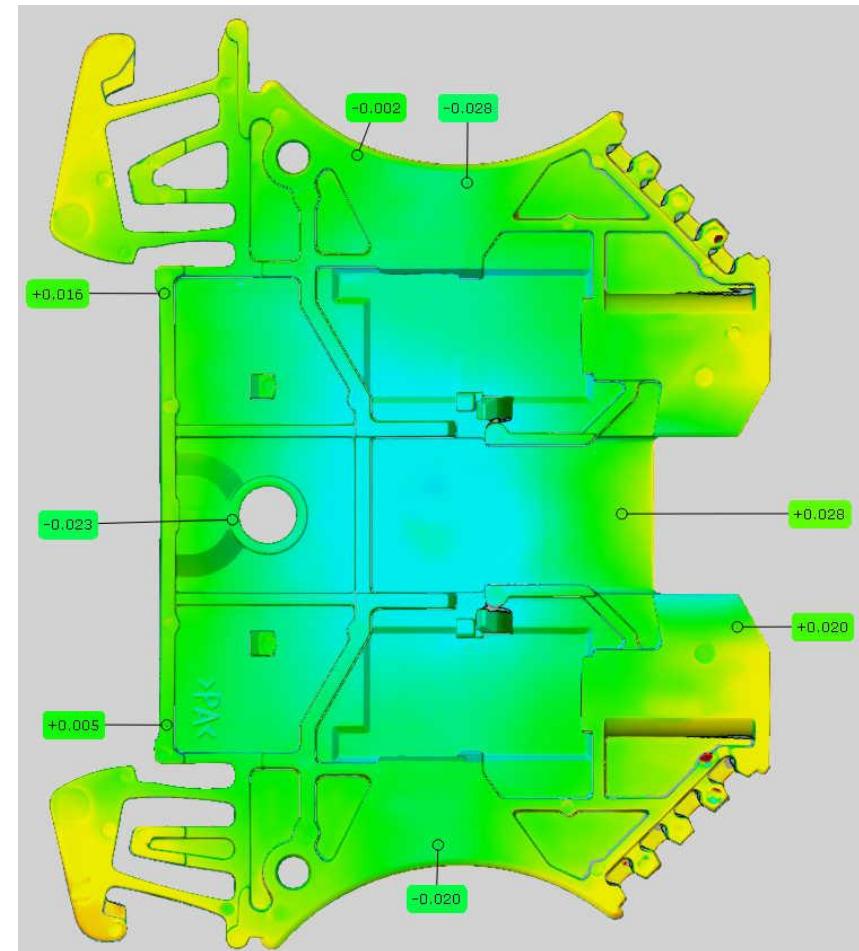
# 同零件不同條件的差異分析 / 保壓時間差異



條件A

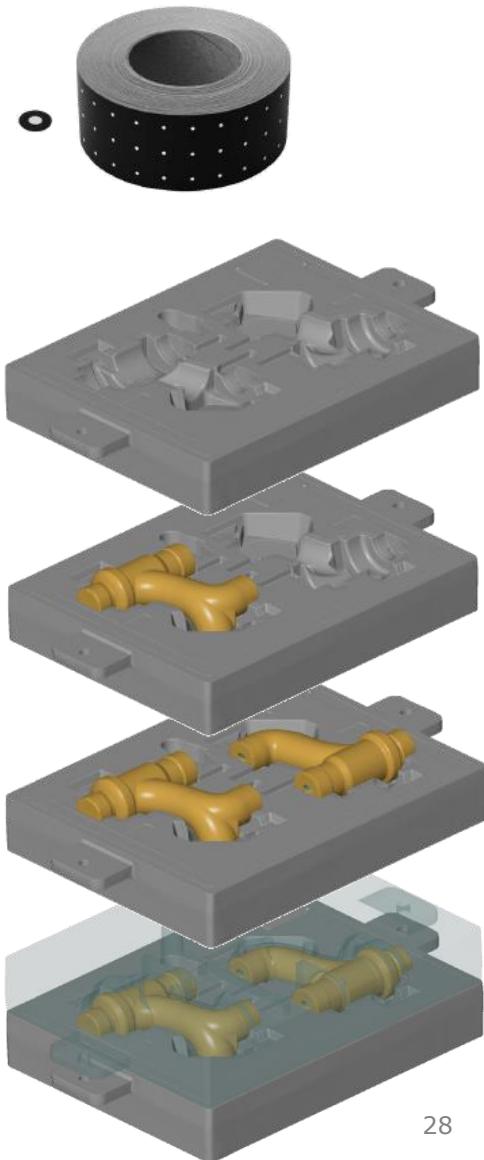


條件B



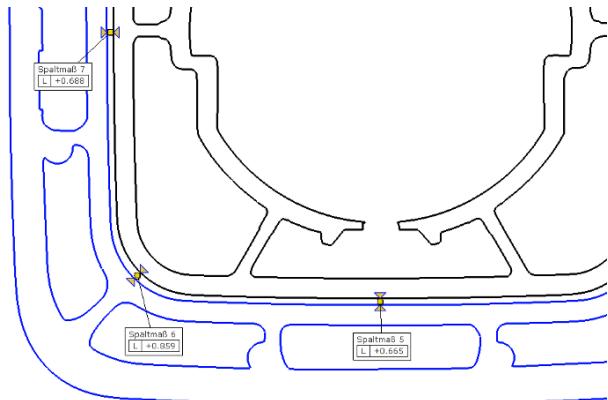
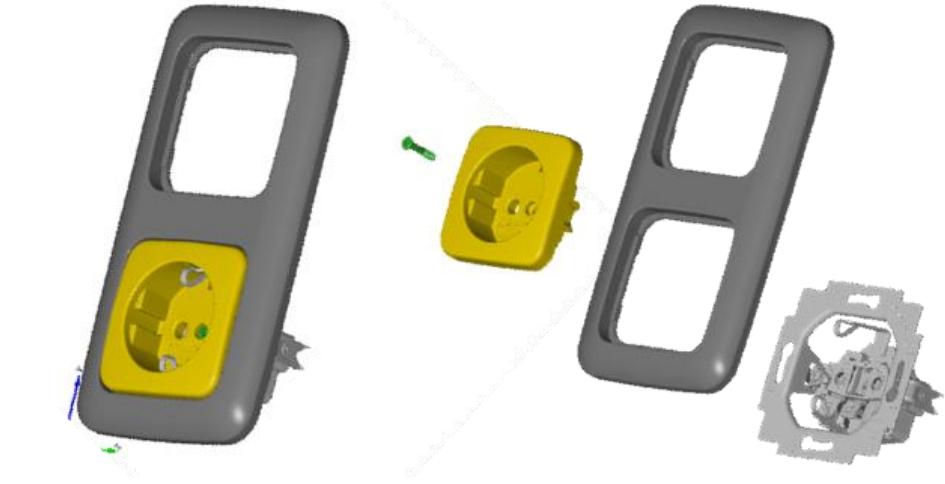
## 多零件虛擬裝配

- 零件在組立狀態先量測外形及標籤點
- 各別零件拆開後進行完整掃描
- 以參考點將各別的零件對位到原先組立狀態的共同座標系



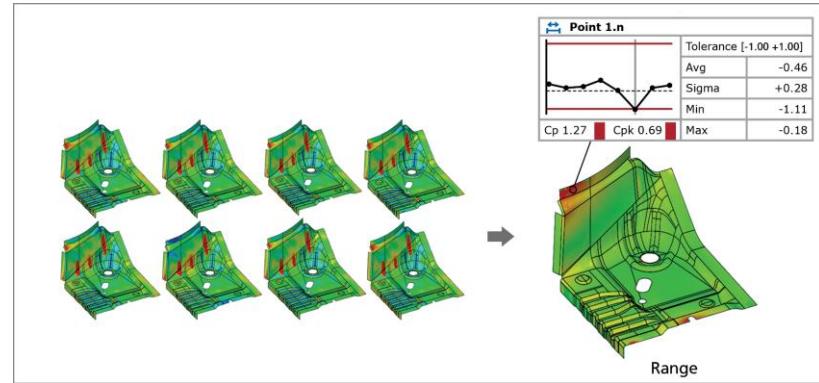
## 多零件虛擬裝配

- 以虛擬尺規或距離量測作間隙分析
- 任一點資料為參考, 以誤差比對分析與對手件的間隙 (全曲面間隙色彩圖)
- 應用面向 : 間隙分析, 干涉分析...等

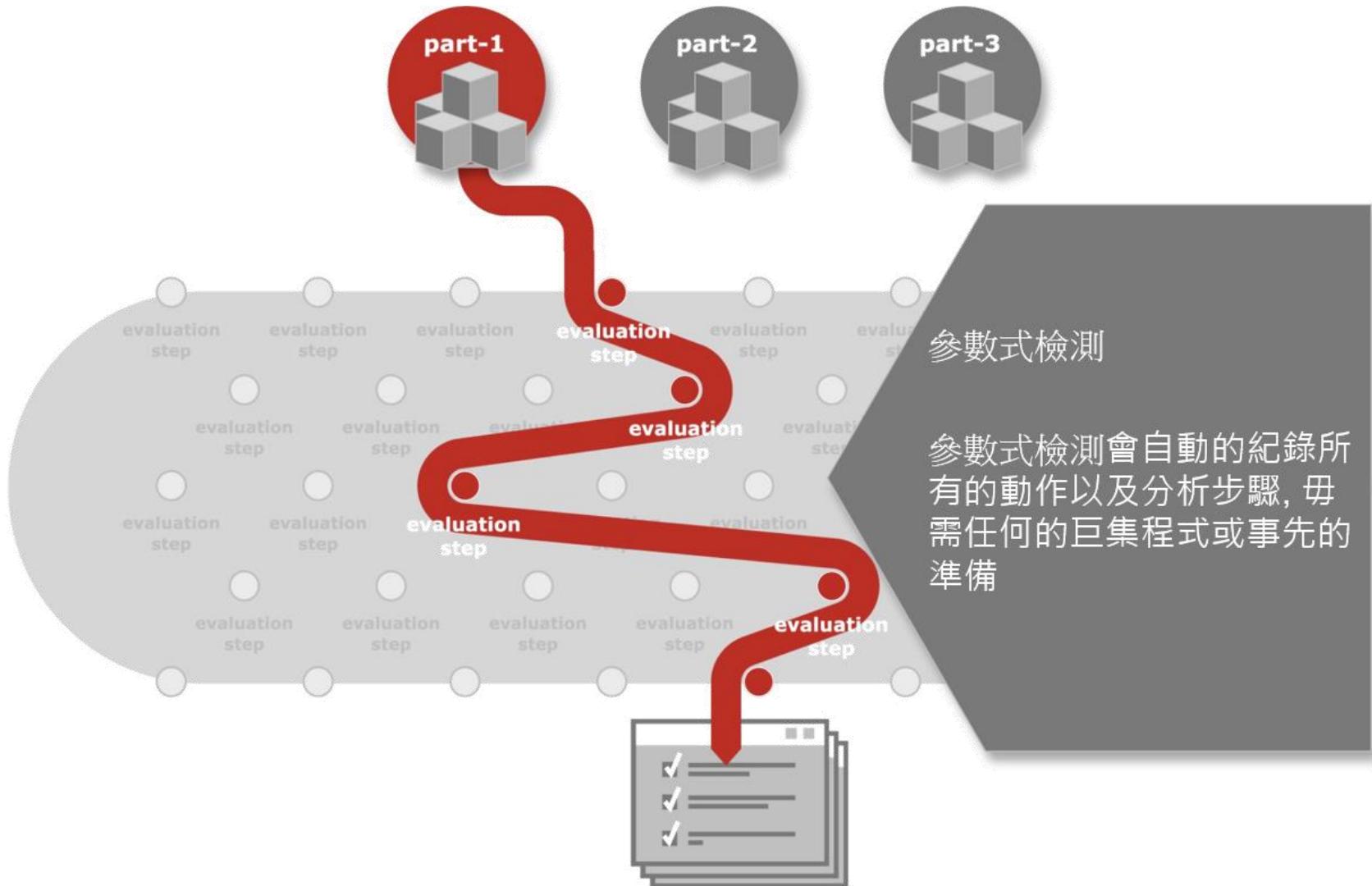


## Trend analysis 趨勢分析應用

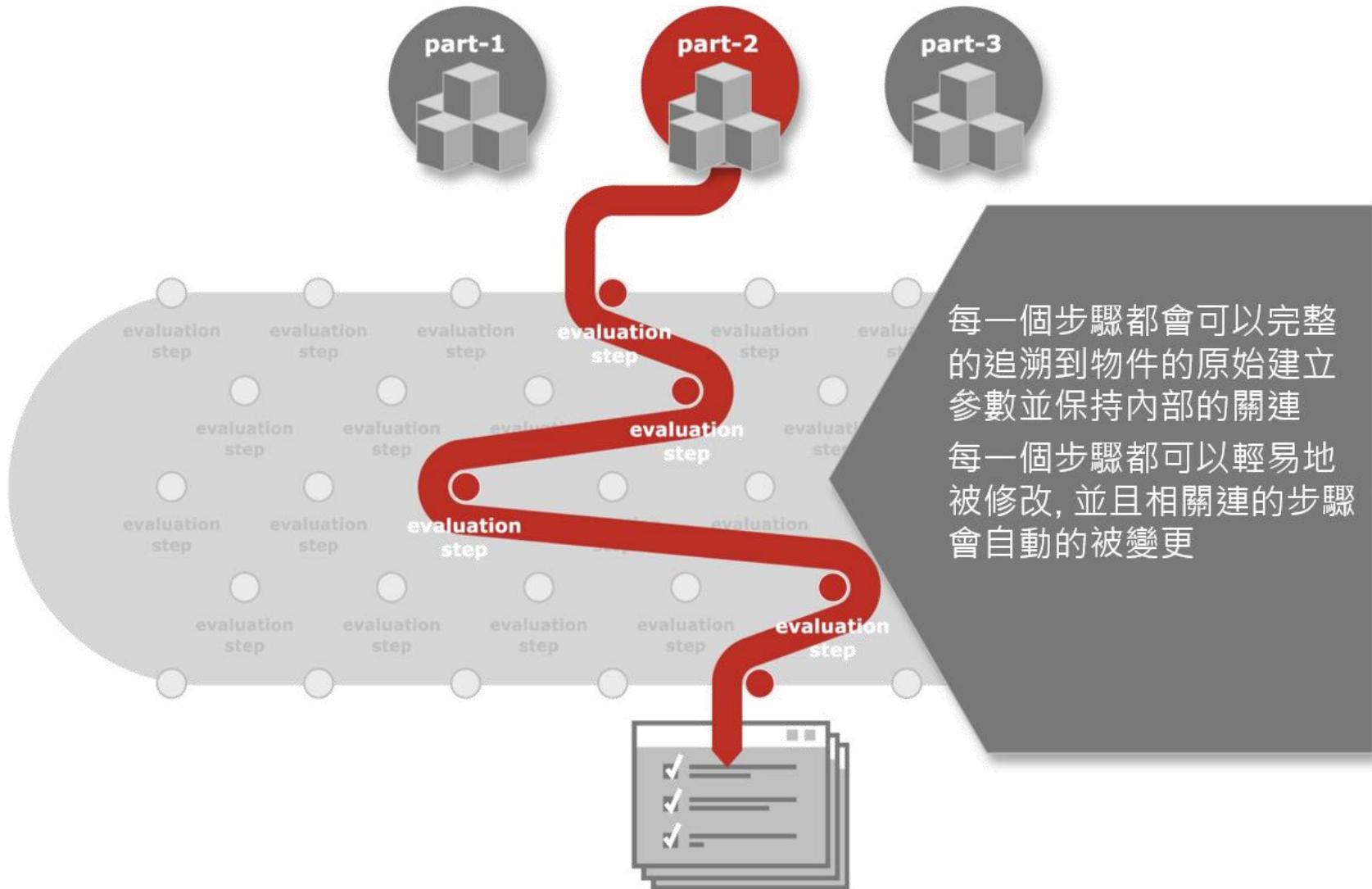
- Control Chart & Colormap
- Pp / Ppk
- Cp / Cpk
- Sigma
- Max. / Min.
- Average
- Range



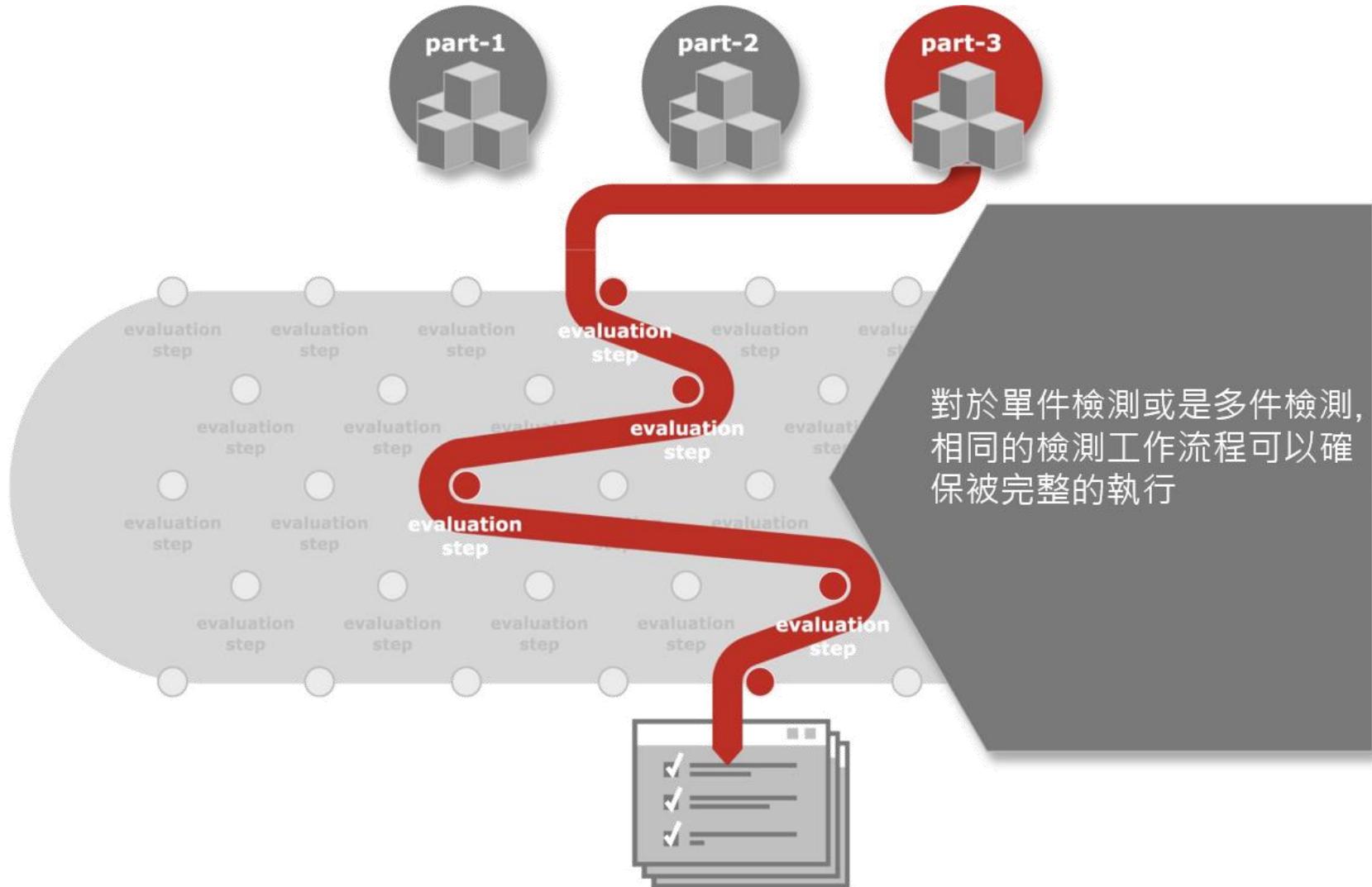
# 參數式檢測 (Teaching by Doing)



## 參數式檢測 (Teaching by Doing)



# 參數式檢測 (Teaching by Doing)

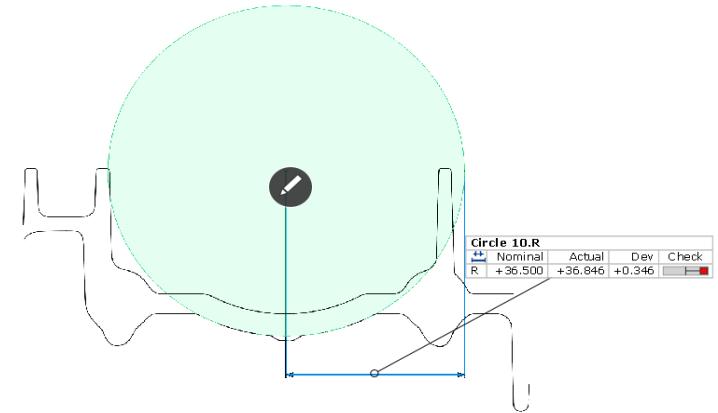


# 重覆件全尺寸檢測

完全不需編輯任何程式，所有檢測內容與資料製作過程步驟，都自動記錄下來，作第二件檢測報告時，僅須導入量測資料重新更新運算，即可快速完成第二件報告。

**優點：**

- 無需透過程式編寫，來達成自動化
- 所有量測內容均相同
- 檢測報告可直接輸出Excel檔，與廠內FAI表格整合
- 大幅提升量測效率

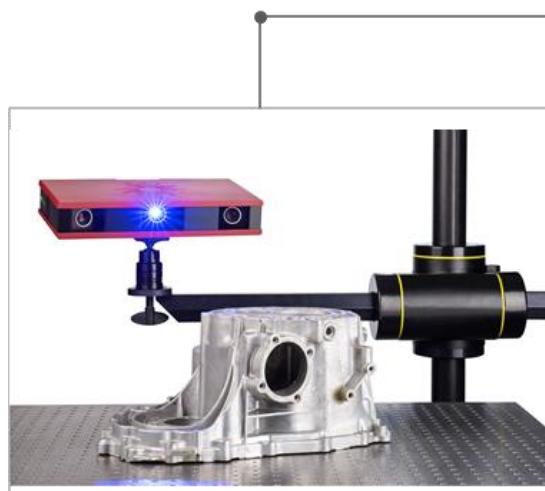


Q5										
	A	B	C	D	E	F	G	H	I	
1	Element	Property	Nominal	Actual	Tol -	Tol +	Dev	Check	Out	
2	Circle 3.R	R	6	6.052	-0.3	0.3	0.052	0.052		
3	Circle 7.R	R	12	11.981	-0.3	0.3	-0.019	-0.019		
4	Circle 8.R	R	15	14.972	-0.3	0.3	-0.028	-0.028		
5	Circle 9.D	D	63	63.22	-0.3	0.3	0.22	0.22		
6	Circle 10.R	R	36.5	36.846	-0.3	0.3	0.346	0.346	0.046	
7	Dimension 1	Lz	22.5	22.404	-0.3	0.3	-0.096	-0.096		
8	Dimension 2	Lz	38.5	38.481	-0.3	0.3	-0.019	-0.019		
9	Dimension 7	L	60	59.965	-0.3	0.3	-0.035	-0.035		
10	Dimension 37	Lx	31.73	31.494	-0.3	0.3	-0.236	-0.236		
11	Dimension 45	L	11	10.948	-0.3	0.3	-0.052	-0.052		
12	Dimension 46	L	13.5	13.482	-0.3	0.3	-0.018	-0.018		
13	Dimension 47	L	17.6	17.507	-0.3	0.3	-0.093	-0.093		
14	Dimension 48	L	21	20.965	-0.3	0.3	-0.035	-0.035		
15	Dimension 50	L	31.2	31.301	-0.3	0.3	0.101	0.101		
16	Dimension 51	L	11	10.93	-0.3	0.3	-0.07	-0.07		
17	Dimension 57	L	9	8.965	-0.3	0.3	-0.035	-0.035		
18	Dimension 58	L	18	17.804	-0.3	0.3	-0.196	-0.196		
19	Dimension 76	L	16	16.052	-0.3	0.3	0.052	0.052		
20	Dimension 77	L	11.73	11.528	-0.3	0.3	-0.202	-0.202		
21	Dimension 78	L	8.5	8.474	-0.3	0.3	-0.026	-0.026		
22	Dimension 79	L	7	6.996	-0.3	0.3	-0.004	-0.004		
23	Dimension 82	L	10	9.779	-0.3	0.3	-0.221	-0.221		
24	Dimension 83	L	3.5	3.487	-0.3	0.3	-0.013	-0.013		
25	Dimension 89	L	23.5	23.468	-0.3	0.3	-0.032	-0.032		
26	Dimension 90	L	27.6	27.523	-0.3	0.3	-0.077	-0.077		
27	Dimension 91	L	16	15.773	-0.3	0.3	-0.227	-0.227		
28	Dimension 92	L	16	15.802	-0.3	0.3	-0.198	-0.198		
29	Dimension 93	L	10.9	10.77	-0.3	0.3	-0.13	-0.13		
30	Dimension 95	L	7	7.007	-0.3	0.3	0.007	0.007		
31	Dimension 99	L	9.5	9.434	-0.3	0.3	-0.066	-0.066		
32	Dimension 102	L	6.5	6.504	-0.3	0.3	0.004	0.004		
33	Dimension 121	L	11	10.934	-0.3	0.3	-0.066	-0.066		

# ATOS Core 高精度3D量測系統



**One sensor head | modular design | easy setup**



**Mobile Measurement System**



**Stationary System**

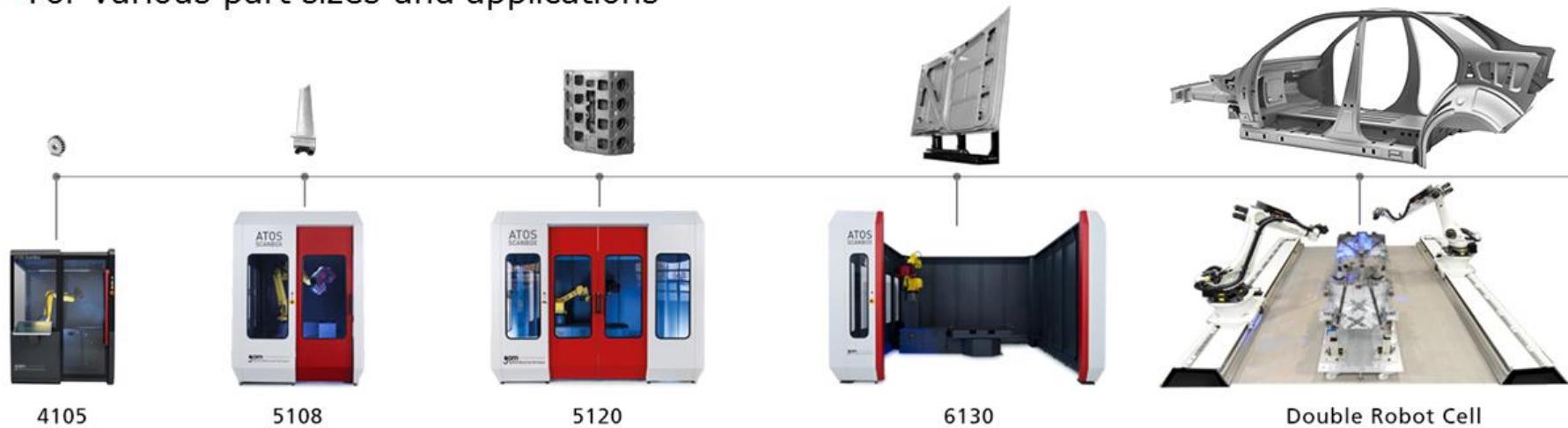


**Automated Measuring Cell**

# ATOS Core 高精度3D量測系統



- Automated 3D measuring technique
- Mobile standard coordinate measurement machines
- For various part sizes and applications





## 馬路科技 – 3D量測專家

Thank you for your attention.

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